Introduction

This application note provides information on converting uM-FPU V3.1 code to uM-FPU64 code. The uM-FPU64 was designed to be software compatible with the uM-FPU V3.1, but there are a few uM-FPU V3.1 instructions that are not directly supported by uM-FPU64. They are as follows:

- COPYI
- EECALL, ELOAD, ELOADA, EEREAD, EESAVE, EESAVEA, EEWRITE
- LOADCON
- RDBLK, WRBLK
- SETOUT

If none of these instructions are used in the uM-FPU V3.1 code, the code will run on uM-FPU64 with no modifications.

This application note provides an overview of different features provided by uM-FPU64, instruction changes, new and modified instructions, and converting from 32-bit calculations to 64-bit calculations. For a full description of the uM-FPU64 chip, please refer to the uM-FPU64 Datasheet, uM-FPU64 Instruction Set, and additional documentation on the Micromega website.

uM-FPU64 Features that are Different from uM-FPU V3.1

64-bit support

In addition to the 128 32-bit registers (numbered 0 to 127) provided by uM-FPU V3.1, the uM-FPU64 also has 128 64-bit registers (numbered 128 to 255). All floating point and integer math operations support both 32-bit and 64-bit operations (excluding MOP and FFT which are 32-bit only).

3.3V operating voltage

The uM-FPU64 has an operating voltage of 3.3V, but the SPI and I²C interfaces are 5V tolerant, and selected digital I/O pins are also 5V tolerant.

No EEPROM

There is no EEPROM on the uM-FPU64 chip, but local RAM or local peripheral devices can be used for data storage on the uM-FPU64.

Digital I/O and Support for Local Peripheral Devices

Extensive digital input and output support is provided, and built-in support for local peripherals including: asynchronous serial interface (with optional hardware flow control), local SPI bus, local FC bus, local 1-Wire bus, LCD display, VDRIVE2 (USB storage). The local peripheral devices can be assigned to any of the digital pins.

Expanded ADC Support
The ADC has multiple channels and DMA support. Using DMA support, data can be sampled at faster data rates.

**Local RAM**

Provides general data storage and can be used for handling data from the local peripherals.

**Background Event Processing**

User-defined functions can be defined to handle background events (e.g. serial input, GPS input, analog-to-digital conversion completion, real-time events, etc.) Foreground/background processing is supported.

**Field Upgradable Firmware**

New firmware can be downloaded from the internet and loaded to the uM-FPU64 using the uM-FPU64 IDE software.

**uM-FPU V3.1 Instruction Changes**

The following uM-FPU V3.1 instructions have been removed from the uM-FPU64 instruction set or have been replaced by new instructions:

- COPYI
- EECALL, ELOAD, ELOADA, EEREAD, EESAVE, EESAVEA, EEWRITE
- LOADCON
- RDBLK, WRBLK
- SETOUT

**COPYI**

The COPYI instruction (uM-FPU V3.1) has been replaced by the LCOPYI and FCOPYI instructions (uM-FPU64). COPYI uses an unsigned byte, while LCOPYI and FCOPYI use a signed byte.

**uM-FPU V3.1**

- COPYI, unsignedByte, register
  - Converts an unsigned byte to a 32-bit integer, and stores it to the specified register.

**uM-FPU64**

- LCOPYI, signedByte, register
  - Converts a signed byte to a 32-bit or 64-bit integer and stores the value in the specified register.
- FCOPYI, signedByte, register
  - Converts a signed byte to a 32-bit or 64-bit floating point value and stores it in the specified register.

**Suggested changes:**

If the COPYI instruction uses an unsigned byte with a value of 0 to 127, then:

- COPYI, unsignedByte

  is replaced by:

- LCOPYI, signedByte

If the COPYI instruction uses an unsigned byte with a value of 128 to 255 then:

- COPYI, unsignedByte

  is replaced by:

- LONGBYTE, unsignedByte
- COPY0, register
**EECALL, EELOAD, ELOADA, EEREAD, EESAVE, EESAVEA, EEWRITE**

There is no EEPROM on the uM-FPU64, so all EEPROM instructions have been removed from the uM-FPU64 instruction set.

*Suggested changes:*

The uM-FPU64 DEVIO instruction provides local device support, including local SPI and I2C bus support. This can be used to interface an external SPI or I2C EEPROM chip, or other device, directly to the uM-FPU64 chip for reading and writing data.

**LOADCON**

The uM-FPU V3.1 LOADCON instruction has been removed from the uM-FPU64 instruction set. LOADCON loads a floating point constant to register 0. It can be replaced by the FWRITE0 instruction, using the floating point value for the constant. The constants are listed in the *uM-FPU V3.1 Instruction Set* document.

*Suggested changes:*

For example, to load the constant for the acceleration of gravity:

```text
LOADCON, 14
```

is replaced by:

```text
FWRITE0, 9.80665
```

**RDBLK, WRBLK**

The uM-FPU V3.1 RDBLK instructions is used to read multiple 32-bit values from sequential registers (using register X). The uM-FPU V3.1 WRBLK instructions is used to write multiple 32-bit values to sequential registers (using register X). These instructions have been replaced on uM-FPU64 by the RDIND and WRIND instructions. These instructions are more comprehensive, and use indirect pointers to provide support for reading and writing multiple 8-bit, 16-bit, 32-bit and 64-bit values. The values are automatically converted as required, between integer and floating point, and between data sizes.

*Suggested changes:*

The uM-FPU V3.1 instruction sequence to write twenty 32-bit floating point values to registers 10 through 29:

```text
SELECTX, 10
WRBLK, 20
{send twenty 32-bit floating point values}
```

is replaced by:

```text
SELECTA, 1
SETIND, REG_FLOAT, 10
WRIND, FLOAT32, 1, 20
{send twenty 32-bit floating point values}
```

The SETIND instruction loads register 1 with a pointer to register 10. The WRIND instruction uses the indirect pointer in register 1 to determine where to store the twenty 32-bit floating point values. If the destination was a 64-bit register, an automatic 32-bit to 64-bit conversion is done. See the *uM-FPU64 Instruction Set* for more details.

**SETOUT**

The uM-FPU V3.1 SETOUT instruction is used to output digital values to pins OUT1 and OUT2. The uM-FPU64 replaces this instruction with the DIGIO instruction, which supports digital input and output to pins D0 to D22.

The action byte for the uM-FPU V3.1 SETOUT instruction is as follows:
<table>
<thead>
<tr>
<th>Action</th>
<th>IDE Symbol</th>
<th>IDE Value</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>LOW</td>
<td>0x00</td>
<td>Set pin as output. Set pin to low.</td>
<td></td>
</tr>
<tr>
<td>HIGH</td>
<td>0x20</td>
<td>Set pin as output. Set set to high.</td>
<td></td>
</tr>
<tr>
<td>TOGGLE</td>
<td>0x40</td>
<td>Set pin as output. Toggle pin level.</td>
<td></td>
</tr>
<tr>
<td>INPUT</td>
<td>0x60</td>
<td>Set pin as input. Read pin value and set Z</td>
<td></td>
</tr>
<tr>
<td>WRITE_BITS</td>
<td>0x80</td>
<td>Write serial value to pin.</td>
<td></td>
</tr>
<tr>
<td>READ_BITS</td>
<td>0xA0</td>
<td>Read serial value from pin.</td>
<td></td>
</tr>
<tr>
<td>WRITE_BITP</td>
<td>0xC0</td>
<td>Write parallel value to pins.</td>
<td></td>
</tr>
<tr>
<td>READ_BITP</td>
<td>0xE0</td>
<td>Read parallel value from pins.</td>
<td></td>
</tr>
</tbody>
</table>

**Suggested changes:**
The following uM-FPU V3.1 instructions set OUT0 low, then high.

```
SETOUT, $00
SETOUT, $01
```

is replaced by the following uM-FPU64 instructions to set D0 low, then high:

```
DIGIO, LOW+D0
DIGIO, HIGH+D0
```

**New Instructions in uM-FPU64**
The following instructions have been added to the uM-FPU64 instruction set:

**SETIND, ADDIND, COPYIND, RDIND, WRIND**
Expanded indirect pointer support.

**DELAY**
Delay in milliseconds.

**DEVIO**
Local peripheral device support.

**DIGIO**
Digital input/output on pins D0 to D22.
DREAD, DWRITE
64-bit read and write.

EVENT
Background event processing.

LBIT
Clear, set, toggle, and test bits.

LCOPYI, FCOPYI
Copy 8-bit unsigned value to a register and convert to integer or floating point value.

LSHIFTI, LORI, LANDI
Shift, bitwise-AND, or bitwise-OR operation using immediate value.

RTC
Real-time clock support.

SETARGS
Enables parameter passing mechanism for FCALL.

SETREAD
Issued prior to all read operations to set the read mode and ensure that the foreground process is active.

Note: If background processing is enabled (see EVENT instruction), then SETREAD must precede all read operations. If background processing is not used, SETREAD is optional, but it’s a good idea to use this instruction for all new code, to ensure it’s compatible if background processing is used in the future.

uM-FPU V3.1 instructions Modified in uM-FPU64

The following instructions have been been modified in uM-FPU64:

All Math Instructions (except MOP and FFT)
Support both 32-bit and 64-bit operations.

ADLOAD, ADCLONG, ADCMODE, ADCSCALE
Supports multiple ADC channels on pins AN0 to AN8. ADCMODE provides additional modes and configurations. ADCSCALE supports both scale and offset.

SERIN, SEROUT
Supports serial input/output to both SERIN/SEROUT, and the DEVIO, ASYNC device.

Converting from 32-bit Calculations to 64-bit Calculations

The uM-FPU64 chip was designed to use the same instruction set as uM-FPU V3.1, so it’s easy to move existing code from uM-FPU V3.1 to uM-FPU64. Likewise, since the same instructions are used, it’s easy to convert 32-bit calculations to 64-bit calculations - it simple requires changing the register definitions.

Registers
The uM-FPU V3.1 chip has 128 32-bit registers numbered 0 to 127.

Registers 0 to 127 32-bit registers
The uM-FPU64 chip has the same 128 32-bit registers numbered 0 to 127, but also has 128 64-bit registers numbered 128 to 255.

- Registers 0 to 127: 32-bit registers
- Registers 128 to 255: 64-bit registers

**Register A**

Register A determines if the operation is 32-bit or 64-bit. If register A selects a 32-bit register, the calculations are performed using 32-bit operations. If register A selects a 64-bit register, the calculations are performed using 64-bit operations.

**Register 0 and 128**

On the uM-FPU V3.1 chip, many instructions implicitly load 32-bit values to register 0 (e.g. the **LOADBYTE**, **LOADWORD**, etc.). On the uM-FPU64 chip, these instructions can load a 32-bit value to register 0, or a 64-bit value to register 128. If register A selects a 32-bit register, a 32-bit value is loaded to register 0. If register A selects a 64-bit register, a 64-bit value is loaded to register 128.

**Converting from 32-bit to 64-bit**

To convert 32-bit calculations to 64-bit calculations, you simply reassign the registers from the 32-bit register bank (registers 0 to 127) to the 64-bit register bank (registers 128 to 255).

The following examples assume that registers 1 and 2 contain a 32-bit floating point value, and registers 129 and 130 contain a 64-bit floating point value.

The following example adds two 32-bit numbers.

```
SELECTA, 1 ; select register 1 as reg[A]
```

By simply changing the register definitions, the following example adds two 64-bit numbers.

```
SELECTA, 129 ; select register 129 as reg[A]
FADD, 130 ; reg[A] = reg[A] + reg[130] (64-bit floating point operation)
```

Conversions between 32-bit and 64-bit values are handled automatically. If register A is 32-bit, but one of the operands is 64-bit, the operand will be converted to 32-bit before the calculation. If register A is 64-bit, but one of the operands is 32-bit, the operand will be converted to 64-bit before the calculation. The conversion is done inside the instruction, the original value in the operand register is unchanged.

The following example adds a 64-bit number to a 32-bit number.

```
SELECTA, 1 ; select register 1 as reg[A]
FADD, 130 ; reg[A] = reg[A] + reg[130]
; the value from reg[130] is converted to 32-bit floating point
; before being added to reg[A]
```

The following example adds a 32-bit number to a 64-bit number.

```
SELECTA, 129 ; select register 129 as reg[A]
```
; the value from reg[2] is converted to 64-bit floating point
; before being added to reg[A])

Further Information
See the Micromega website (http://www.micromegacorp.com) for additional information regarding the uM-FPU64 floating point coprocessor, including:

  uM-FPU64 Datasheet
  uM-FPU64 Instruction Set